

## 11 Preliminaries for MDPs in continuous time

### 11.1 Markov processes in continuous time

A stochastic process in continuous time is a collection of random variables  $\{X_t\}_{t \geq 0}$ , where each  $X_t$  takes values in some *state space*  $\mathcal{X}$ , and the time variable  $t$  takes values in  $\mathbb{R}_+ := [0, \infty)$ . The Markov property in continuous time is described similar to the discrete-time case, by sampling the continuous-time process at an arbitrary finite set of time instants:

**Definition 11.1** A stochastic process  $\{X_t\}_{t \geq 0}$  is said to have the Markov property if, for any sequence of times  $0 \leq t_1 < \dots < t_m < t$  and for any  $A \in \mathcal{B}(\mathcal{X})$ ,

$$\mathbf{P}[X_t \in A | X_{t_1}, \dots, X_{t_m}] = \mathbf{P}[X_t \in A | X_{t_m}].$$

We also define *transition kernels* of a Markov process: For  $0 \leq s < t$  and  $A \in \mathcal{B}(\mathcal{X})$ ,

$$\mathcal{P}_{s,t}(x, A) := \mathbf{P}[X_t \in A | X_s = x]$$

A transition kernel of a Markov process has the following properties:

1. For  $s, t, A$  fixed,  $x \mapsto \mathcal{P}_{s,t}(x, A)$  is measurable.
2. For  $s, t, x$  fixed,  $A \mapsto \mathcal{P}_{s,t}(x, A)$  is a probability measure on  $(\mathcal{X}, \mathcal{B}(\mathcal{X}))$ .
3. (Chapman-Kolmogorov equation) For all  $0 \leq r < s < t$  and for all  $x, A$ ,

$$\mathcal{P}_{r,t}(x, A) = \int_{\mathcal{X}} \mathcal{P}_{s,t}(x', A) \mathcal{P}_{r,s}(x, dx').$$

In this course, we will consider two cases:  $\mathcal{X} = \{1, \dots, n\}$  and  $\mathcal{X} = \mathbb{R}^n$ .

### 11.2 Finite-state case

Consider finite state-space  $\mathcal{X} = \{1, 2, \dots, n\}$  and a Markov process  $\{X_t\}_{t \geq 0}$  on  $\mathcal{X}$ . Let  $\mu_t(\cdot) := \mathbf{P}[X_t = \cdot]$  be the probability mass function of  $X_t$ . In finite-state case, the transition probabilities are given by a matrix defined for all  $s, t$  with  $0 \leq s < t$ :

$$P_{s,t} = [\mathcal{P}_{s,t}(a, b)]_{a,b \in \mathcal{X}}$$

For any  $0 \leq t_1 < t_2 \dots < t_m$ , we have

$$\begin{aligned} \mathbf{P}[X_{t_1} = a_1, \dots, X_{t_m} = a_m] &= \mathbf{P}[X_{t_1} = a_1] \mathbf{P}[X_{t_2} = a_2 | X_{t_1} = a_1] \dots \mathbf{P}[X_{t_m} = a_m | X_{t_{m-1}} = a_{m-1}] \\ &= \mu_{t_1}(a_1) \cdot \prod_{j=1}^{m-1} P_{t_j, t_{j+1}}(a_j, a_{j+1}). \end{aligned}$$

Therefore  $\mu_0, \{P_{s,t}\}_{0 \leq s < t}$  completely characterize the MP. Since the map  $\mu_s \mapsto \mu_t$  is defined by  $\mu_t(i) = \sum_{j \in \mathcal{X}} \mu_s(j) P_{s,t}(j, i)$ , we can express this in a matrix form:

$$\mu_t = \mu_s P_{s,t}, \quad \forall 0 \leq s < t$$

for row vector  $\mu$ . The C-K equation is also represented using matrix multiplication:

$$P_{r,t} = P_{r,s}P_{s,t}, \quad \forall 0 \leq r < s < t$$

**Definition 11.2** A Markov process  $\{X_t\}_{t \geq 0}$  on  $\mathcal{X}$  is time-homogeneous if for any  $0 \leq s < t$ ,  $i, j \in \mathcal{X}$ :

$$\mathbf{P}[X_t = j | X_s = i] = \mathbf{P}[X_{t-s} = j | X_0 = i]$$

With slightly abusive notation, we denote

$$P_{t-s} := P_{0,t-s} = P_{s,t}$$

Now it seems  $\mu_0, \{P_t\}_{t \geq 0}$  can completely characterize a time-homogeneous Markov process in finite-state case. However, it turns out that we only need a single matrix called *transition intensity*.

### 11.2.1 Transition intensity matrix

We define Q-matrices as following:

$$\Lambda = [\lambda_{i,j}]_{i,j \in \mathcal{X}} \quad \text{s.t.} \quad \begin{cases} \lambda_{i,j} \geq 0, & \text{for } i \neq j \\ \sum_j \lambda_{i,j} = 0, & \forall i \in \mathcal{X} \end{cases}$$

Given a finite-state Markov process characterized by  $\mu_0, \{P_t\}_{t \geq 0}$ , consider the derivative of  $P_t$ :

$$\left. \frac{d}{dt} P_t \right|_{t=0} = \lim_{h \downarrow 0} \frac{P_h - P_0}{h} = \lim_{h \downarrow 0} \frac{P_h - I_n}{h} =: \Lambda$$

Without proof we claim that the limit exists, and moreover, it is a Q-matrix. We call  $\Lambda$  the transition intensity of the finite-state Markov process. Since

$$\begin{aligned} \mu_h &= \mu_0 P_h = \mu_0 (I_n + h\Lambda + o(h)) \\ \Rightarrow \mu_h &= \mu_0 + h\mu_0\Lambda + o(h) \Rightarrow \frac{\mu_h - \mu_0}{h} = \mu_0\Lambda + o(1) \\ \Rightarrow \frac{\mu_{t+h} - \mu_t}{h} &= \mu_t\Lambda + o(1) \end{aligned}$$

we conclude the *forward Kolmogorov equation*:

$$\frac{d\mu_t}{dt} = \mu_t\Lambda$$

Let us investigate the other direction. Given a Q-matrix  $\Lambda$ , can a Markov process be constructed? We first prove the following statement. For fixed  $\mu \in \mathcal{P}(\mathcal{X})$ , consider an ordinary differential equation:

$$\frac{d\mu_t}{dt} = \mu_t\Lambda, \quad \mu_0 = \mu$$

if  $\Lambda$  is a Q-matrix, then  $\mu_t \in \mathcal{P}(\mathcal{X})$  for all  $t \geq 0$ .

*Proof:* The solution to the ODE is given by  $\mu_t = \mu e^{t\Lambda}$ . We first prove that the matrix exponential

$e^{t\Lambda}$  has non-negative entries if  $\Lambda$  is a Q-matrix. Let  $\lambda := \max_i \sum_{j \neq i} \lambda_{i,j}$ , and define  $R := I_n + \frac{1}{\lambda} \Lambda$  where  $I_n$  is  $n$ -dimensional identity matrix. It is easy to see  $R$  has non-negative entries, and therefore

$$e^{\lambda t R} = \sum_{k=0}^{\infty} \frac{(\lambda t)^k}{k!} R^k$$

has non-negative entries. Now it is straightforward that

$$e^{t\Lambda} = e^{\lambda t R - \lambda t I_n} = e^{-\lambda t} e^{\lambda t R}$$

also has non-negative entries. Upon using this fact,  $\mu e^{t\Lambda}$  is element-wise non-negative. Let  $\mathbf{1}$  be  $n$ -dimensional column vector with 1 for all its elements. Then

$$\frac{d}{dt}(\mu_t \mathbf{1}) = \mu_t \Lambda \mathbf{1} = 0$$

Therefore  $\mu_t \mathbf{1} = \mu \mathbf{1} = 1$ , since  $\mu \in \mathcal{P}(\mathcal{X})$ . Since  $\mu_t(\cdot) \geq 0$  and  $\mu_t \mathbf{1} = 1$ ,  $\mu_t \in \mathcal{P}(\mathcal{X})$ . ■

Now we claim the following proposition.

**Proposition 11.1** *For a given Q-matrix  $\Lambda$  and an arbitrary initial distribution, a stochastic process on  $\mathcal{X}$  is well-defined via forward Kolmogorov equation. Moreover, it is a time-homogeneous Markov process with transition probability matrix  $P_t$  given by the following ODE:*

$$\frac{dP_t}{dt} = P_t \Lambda \quad P_0 = I_n$$

*Proof:* The first statement is natural consequence of the previous claim. The Markov property is justified by choosing initial condition by  $\mu_{t_m}(i) = 1_{i=a_m}$ . From the forward equation,

$$\mu_h = \mu_0 P_h = \mu_0 (I_n + h\Lambda + o(h))$$

Since  $\mu_0$  may be arbitrarily chosen in probability simplex, we conclude

$$\begin{aligned} P_h &= I_n + h\Lambda + o(h) \\ \Rightarrow \frac{P_h - I_n}{h} &= \Lambda + o(1) \\ \Rightarrow \frac{P_h P_t - P_t}{h} &= \Lambda P_t + o(1) \end{aligned}$$

By C-K equation,  $P_h P_t = P_{0,h} P_{h,t+h} = P_{t+h}$ , we conclude

$$\frac{dP_t}{dt} = \Lambda P_t \quad P_0 = I_n$$

Also note that  $P_t P_h = P_{0,t} P_{t,h} = P_{t+h}$ , and hence  $\frac{dP_t}{dt} = P_t \Lambda$ , that is,  $P_t$  and  $\Lambda$  commute. ■

### 11.2.2 Uniformization trick

Given  $(\mu_0, \Lambda)$ , recall the matrix  $R = I_n + \frac{1}{\lambda}\Lambda$ . It is in fact a row-stochastic matrix, that is, every entry is non-negative and  $\sum_j R_{i,j} = 1$ . Therefore, we can define a discrete-time Markov process  $\{\xi_k\}_{k=0}^\infty$  with  $\xi_0 \sim \mu_0$  and one-step transition probability matrix is  $R$ . We also define  $\{N_t\}_{t \geq 0}$  be an independent Poisson process with rate  $\lambda$ , then

$$\mathbf{P}[N_t = k] = e^{-\lambda t} \frac{(\lambda t)^k}{k!}$$

Now we claim the following: Let  $\hat{X}_t := \xi_{N_t}$  then  $\hat{X}_t$  and  $X_t$  have the same probability distribution at each  $t \geq 0$ .

*Proof:* We already showed that

$$\begin{aligned} \mu_t &= \mu_0 e^{t\Lambda} = \mu_0 e^{-\lambda t} e^{\lambda t R} \\ &= \sum_{k=0}^{\infty} e^{-\lambda t} \frac{(\lambda t)^k}{k!} \mu_0 R^k \end{aligned}$$

and therefore,

$$\begin{aligned} \mu_t(\cdot) &= \sum_{k=0}^{\infty} \mathbf{P}[N_t = k] \mathbf{P}[\xi_k = \cdot] \\ &= \sum_{k=0}^{\infty} \mathbf{P}[N_t = k, \xi_{N_t} = \cdot] \\ &= \mathbf{P}[\hat{X}_t = \cdot] \end{aligned}$$

where we use independence between  $\{N_t\}$  and  $\{\xi_k\}$ , and the law of total probability. ■

## 12 Diffusion processes

Now we consider another class of continuous-time Markov processes, diffusion processes. These have the state space  $\mathcal{X} = \mathbb{R}^n$ . Let  $\{X_t\}_{t \geq 0}$  be a time-homogeneous Markov process with state space  $\mathcal{X} = \mathbb{R}^n$ . We will denote by  $\mathcal{P}_t(\cdot, \cdot)$  its transition kernel: for any  $x \in \mathbb{R}^n$ , Borel set  $B \subseteq \mathbb{R}^n$ ,  $0 \leq s < t$ ,

$$\mathcal{P}_t(x, B) := \mathbf{P}[X_t \in B | X_0 = x] = \mathbf{P}[X_{s+t} \in B | X_s = x].$$

We say it is a *diffusion process* if:

- for any  $x \in \mathbb{R}^n$  and  $r > 0$ ,

$$\lim_{h \downarrow 0} \frac{1}{h} \mathbf{P}[\|X_h - X_0\| > r | X_0 = x] = 0,$$

or,

$$\lim_{h \downarrow 0} \frac{1}{h} \mathcal{P}_h(X, (\mathbb{B}^n(x, r))^c) = 0,$$

where  $\mathbb{B}^n(x, r)^c$  is the complement of the ball in  $(\mathbb{R}^n, \|\cdot\|)$  with center  $x$ , radius  $r$ .

- There exist functions:  $b_i : \mathbb{R}^n \rightarrow \mathbb{R}, i = 1, \dots, n$  and  $A : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$ , such that  $A(x) := (a_{ij}(x))_{i,j=1}^n$  is a symmetric positive-semidefinite  $n \times n$  matrix for any  $x \in \mathbb{R}^n$ , and for any  $x \in \mathbb{R}^n$  and  $r > 0$

$$\lim_{h \downarrow 0} \frac{1}{h} \mathbf{E}[(X_{h,i} - X_{0,i}) \mathbf{1}_{\{\|X_h - X_0\| \leq r\}} | X_0 = x] = b_i(x), \forall i.$$

and

$$\lim_{h \downarrow 0} \frac{1}{h} \mathbf{E}[(X_{h,i} - X_{0,i})(X_{h,j} - X_{0,j}) \mathbf{1}_{\{\|X_h - X_0\| \leq r\}} | X_0 = x] = a_{ij}(x), \forall i, j,$$

i.e.,

$$\begin{aligned} \mathbf{E}[X_h | X_0] &= b(x)h + o(h) \\ \text{Cov}(X_h | X_0) &= A(x)h + o(h) \end{aligned}$$

The vector-valued function  $b : \mathbb{R}^n \rightarrow \mathbb{R}^n$  given by  $b(x) := (b_1(x), \dots, b_n(x))^\top$  is called the (local) *drift* of the diffusion process, while the matrix-valued function  $A : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$  is the (local) *covariance matrix*.

As an example, consider the standard Brownian motion (or Wiener process) in  $\mathbb{R}^n$ . Recall that it is a random process  $\{W_t\}_{t \geq 0}$  on  $\mathbb{R}^n$  satisfying the following:

- $W_0 = 0$ .
- $W_t - W_s \sim \mathcal{N}(0, (t-s)I_n), 0 \leq s < t$ .
- $(W_t - W_s) \perp (W_s - W_r), 0 \leq r < s < t$ .

Then it can be shown that  $\{W_t\}_{t \geq 0}$  is a diffusion process with  $b(x) \equiv 0$  and  $A(x) \equiv I_n$  for all  $x \in \mathbb{R}^n$ .

## 12.1 Forward Kolmogorov equation

Now we will show how one can construct the forward Kolmogorov equation for a diffusion process specified by the pair  $(b(x), A(x))$ . Recall the finite-state case: If  $\{X_t\}_{t \geq 0}$  is a time-homogeneous Markov process with finite state space  $\mathcal{X} = \{1, \dots, n\}$  and the transition intensities matrix  $\Lambda \in \mathbb{R}^{n \times n}$ , then the probability law  $\mu_t(\cdot) := \mathbf{P}[X_t = \cdot]$  evolves according to

$$\frac{d\mu}{dt} = \mu_t \Lambda,$$

with a given initial condition  $\mu_0$ . Explicitly,  $\mu_t = \mu_0 e^{\Lambda t}$ ; in particular, using this with  $\mu_0(x') := \mathbf{1}_{\{x'=x\}}$  for some fixed  $x$  gives the formula for the transition probabilities:  $P_t(x, x') = \mathbf{P}[X_t = x' | X_0 = x] = e^{\Lambda t}(x, x')$  — that is, the entry in row  $x$ , column  $x'$  of  $e^{\Lambda t}$ . We can also use the forward Kolmogorov equation to keep track of the evolution of expected values. Let a function  $f : \mathcal{X} \rightarrow \mathbb{R}^n$  and an initial state  $x \in \mathcal{X}$  be given. Just as we represented probability distributions on  $\mathcal{X}$  by *row vectors*, we can represent such an  $f$  by a *column vector*  $f = (f(1), \dots, f(n))^\top$ . Then

$$\mathbf{E}[f(X_t) | X_0 = x] = \sum_{x' \in \mathcal{X}} P_t(x, x') f(x') = P_t f(x),$$

where the quantity on the right-hand side is obtained by multiplying the column vector  $f$  on the left by the matrix  $P_t$ . Since

$$\frac{dP_t}{dt} = P_t \Lambda = \Lambda P_t, \quad P_0 = I_n$$

it follows that

$$\frac{d}{dt} P_t f = P_t \Lambda f = \Lambda P_t f.$$

It follows directly from definitions that, for each  $t \geq 0$ , the map  $f \mapsto P_t f$  is linear, and it also has the following two crucial properties: if  $f \geq 0$  everywhere, then  $P_t f \geq 0$  everywhere (that is,  $P_t$  preserves positivity) and  $P_t \mathbf{1} = \mathbf{1}$ , where  $\mathbf{1} = (1, 1, \dots, 1)^\top$  is the constant function  $x \mapsto 1$ .

We can develop a similar formalism for diffusion processes. Let  $\{X_t\}_{t \geq 0}$  be a time-homogeneous Markov process on  $\mathbb{R}^n$  with transition kernel  $P_t(x, B)$ . Let a bounded measurable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be given; for each  $t \geq 0$  and each  $x \in \mathbb{R}^n$ , define the function  $P_t f$  by

$$P_t f(x) := \int_{\mathbb{R}^n} f(x') P_t(x, dx') \tag{1}$$

— recall that, for each  $x$  and  $t$ ,  $P_t(x, \cdot)$  is a Borel probability measure on  $\mathbb{R}^n$ , and, in particular, taking  $f(x) = \mathbf{1}_B(x)$  for any Borel set  $B \subseteq \mathbb{R}^n$ , we see that

$$P_t(x, B) = \int_B P_t(x, dx') = \int_{\mathbb{R}^n} \mathbf{1}_B(x') P_t(x, dx') = P_t \mathbf{1}_B(x).$$

It is also easy to see that  $f \mapsto P_t f$  is linear, preserves positivity and constants. Moreover, it follows from the Chapman–Kolmogorov equation that, for any  $s, t \geq 0$ ,  $P_{s+t} = P_s \circ P_t = P_t \circ P_s$  and  $P_0$  is the identity operator:  $P_0 f = f$  for any  $f$  (we say that  $P_t$  has the *semigroup property*).

Now we take the cue from our construction of the transition intensity matrix  $\Lambda$  and consider the limit

$$\lim_{h \downarrow 0} \frac{P_h f - f}{h} =: \mathcal{A}f,$$

provided the limit exists. In other words, for any  $x \in \mathbb{R}^n$ , any sufficiently regular  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , and any small enough  $h > 0$ ,

$$P_h f(x) = f(x) + h \cdot \mathcal{A}f(x) + o(h).$$

Moreover, by time homogeneity and by the semigroup property  $P_{s+t} = P_t \circ P_s$ ,

$$\begin{aligned} P_{t+h}f(x) &= P_t f(x) + h \cdot \mathcal{A}P_t f(x) + o(h) \\ &= P_t f(x) + h \cdot P_t \mathcal{A}f(x) + o(h), \end{aligned}$$

or, equivalently,

$$\mathbf{E}[f(X_{t+h})|X_0 = x] = \mathbf{E}[f(X_t)|X_0 = x] + h \cdot \mathbf{E}[\mathcal{A}f(X_t)|X_0 = x] + o(h)$$

which leads to the forward Kolmogorov equation

$$\frac{dP_t f}{dt} = \mathcal{A}P_t f = P_t \mathcal{A}f, \quad P_0 f = f.$$

The linear operator  $\mathcal{A}$  is called the *generator* of the Markov process; in general, it will be well-defined only for  $f$  in some set  $\mathcal{D}(\mathcal{A})$ , which is called the *domain* of  $\mathcal{A}$ .

Now, it can be shown that, if  $\{X_t\}_{t \geq 0}$  is a diffusion process with drift  $b(x)$  and diffusion matrix  $A(x)$ , then the generator  $\mathcal{A}$  acts on any  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  which is twice continuously differentiable as follows:

$$\mathcal{A}f = b^T \nabla f + \frac{1}{2} \text{tr}(A \nabla^2 f). \quad (2)$$

Coming back to the example of the standard Brownian motion with  $b = 0$  and  $A = I_n$ , we see that it has the generator

$$\begin{aligned} \mathcal{A}f &= b^T \nabla f + \frac{1}{2} \text{tr}(A \nabla^2 f) \\ &= \frac{1}{2} \text{tr} \nabla^2 f \\ &= \frac{1}{2} \Delta f, \end{aligned}$$

where  $\Delta$  is the Laplace operator. Using this, it is not hard to derive the transition kernel of the Brownian motion: let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be a bounded measurable function. Then it is readily verified by direct calculation that the forward Kolmogorov equation

$$\frac{d}{dt} P_t f = \frac{1}{2} \Delta P_t f, \quad P_0 f = f$$

has the solution

$$\begin{aligned} P_t f(x) &= \frac{1}{(2\pi t)^{n/2}} \int_{\mathbb{R}^n} f(x') \exp\left(-\frac{1}{2t} \|x' - x\|^2\right) dx' \\ &= \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} f(x + \sqrt{t}x') \exp\left(-\frac{1}{2} \|x'\|^2\right) dx' \\ &\equiv \mathbf{E}[f(x + \sqrt{t}Z)], \end{aligned}$$

where  $Z \sim \mathcal{N}(0, I_n)$ .

In general, one can extract the drift  $b$  and a diffusion matrix  $A$  from the knowledge of the generator  $\mathcal{A}$ , provided it satisfies some regularity conditions. In particular, suppose that  $\mathcal{A}f(x) := \lim_{h \downarrow 0} \frac{1}{h} (P_h f(x) - f(x))$  has the following properties:

- $\mathcal{A}$  is *local*: if  $f = 0$ , in some neighborhood of  $x$ , then  $\mathcal{A}f = 0$
- $\mathcal{A}$  is *linear*: if  $\mathcal{A}f$  and  $\mathcal{A}g$  are well-defined, then  $\mathcal{A}(c_1f + c_2g) = c_1\mathcal{A}f + c_2\mathcal{A}g$  for any  $c_1, c_2 \in \mathbb{R}$ .
- $\mathcal{A}$  obeys the *minimum principle*: If  $f(x) = \min_{y \in \mathbb{R}^n} f(y)$ , then  $\mathcal{A}(f(y) - f(x)) \geq 0$ .

Then, for each  $x \in \mathbb{R}^n$ , there exist a vector  $b(x) \in \mathbb{R}^n$  and a symmetric positive-semidefinite matrix  $A(x) \in \mathbb{R}^{n \times n}$ , such that

$$\mathcal{A}f(x) = b(x)^T \nabla f(x) + \frac{1}{2} \text{tr}(A(x) \nabla^2 f(x)). \quad (3)$$

One way to construct  $b$  and  $A$  is as follows: Choose any function  $\eta : \mathbb{R}^n \rightarrow \mathbb{R}$  with the following properties:

- $\eta \in C^\infty$ , i.e.,  $\eta$  is infinitely continuously differentiable.
- $\eta(z) = 1$  for  $z \in \mathbb{B}^n(0, 1)$ .
- $\eta(z) = 0$  for  $z \notin \mathbb{B}^n(0, 2)$ .

Given an arbitrary  $x \in \mathbb{R}^n$ , for  $i, j \in [n]$  consider the functions

$$f_i(z) := \eta(z - x)(z_i - x_i), \quad f_{ij}(z) := f_i(z)f_j(z) = \eta^2(z - x)(z_i - x_i)(z_j - x_j).$$

Then it can be shown that  $\mathcal{A}f(x)$  has the form (3) with  $b_i(x) = \mathcal{A}f_i(x)$  and  $a_{ij}(x) = \mathcal{A}f_{ij}(x)$ .

## 12.2 Constructing diffusion processes

Now we are ready to state the following key result: Let a drift  $b(x)$  and a diffusion matrix  $A(x)$  be given. Suppose there exists some constant  $0 < c < \infty$ , such that

$$\text{tr}A(x) + \max\{b(x)^T x, 0\} \leq c(1 + \|x\|^2), \quad \forall x \in \mathbb{R}^n.$$

Then, for any Borel probability measure  $\mu_0$  on  $\mathbb{R}^n$ , there exists a diffusion process  $\{X_t\}_{t \geq 0}$ , such that the probability laws  $\mu_t(\cdot) := \mathbf{P}[X_t \in \cdot]$  satisfy

$$\int f \, d\mu_t = \int f \, d\mu_0 + \int_0^t \left( \int \mathcal{A}f \, d\mu_s \right) \, ds \quad (4)$$

for any  $f$  such that

$$\mathcal{A}f = b^T \nabla f + \frac{1}{2} \text{tr}(A \nabla^2 f)$$

is well-defined. In fact, an explicit construction relies on the following scheme: Choose any factorization  $A(x) = \sigma(x)\sigma(x)^T$  for some  $\sigma(x) \in \mathbb{R}^{n \times r}$  and, for a fixed  $h > 0$ , consider the process  $\{X_t^{(h)}\}_{t \geq 0}$  defined by

$$X_t^{(h)} = X_{kh}^{(h)} + hb(X_{kh}^{(h)}) + \sigma(X_{kh}^{(h)})(W_t - W_{kh}), \quad t \in [kh, (k+1)h),$$

where  $\{W_t\}$  is the standard Wiener process on  $\mathbb{R}^r$ . Then one takes the limit as  $h \downarrow 0$  and obtains a limiting process  $\{X_t\}_{t \geq 0}$  whose marginal laws  $\mu_t$  obey (4). In fact, if  $A(x) \equiv 0$  everywhere, then this is just the familiar Peano–Euler scheme for approximately solving the deterministic ODE

$$dX_t = b(X_t) dt$$

with the *random* initial condition  $X_0 \sim \mu_0$ . Here,  $dX_t$  is shorthand for  $X_{t+dt} - X_t$ . In the next lecture, we will show that we can interpret the diffusion process  $\{X_t\}_{t \geq 0}$  as the solution of a *stochastic differential equation*

$$dX_t = b(X_t) dt + \sigma(X_t) dW_t, \quad X_0 \sim \mu_0$$

where  $dW_t$  is shorthand for infinitesimal increments of the Wiener process:  $dW_t = W_{t+dt} - W_t$ . In order to do this properly, we will introduce the notion of *stochastic integral* due to K. Itô.