

### Problems to be handed in

- 1 Give a direct proof of Theorem 10.2 in the lecture notes using dynamic programming.
- 2 Consider the steady-state Kalman filter, as presented in Section 10.3 of the lecture notes. Suppose the following conditions are met:
  - (i)  $(A, C)$  is an observable pair;
  - (ii) the observation model is nondegenerate, i.e.,  $\Sigma_V \succ 0$ ;
  - (iii) there exists a matrix  $\Gamma$ , such that  $\Sigma_W = \Gamma\Gamma^\top$  and  $(A, \Gamma)$  is a controllable pair.

Prove that the steady-state Kalman filter is asymptotically optimal, i.e., that

$$\lim_{t \rightarrow \infty} \text{Cov}(X_t - \hat{X}_t) = (I - LC)K,$$

where  $K$  is the (unique, positive definite) solution of the discrete algebraic Riccati equation given in Eq. (57).

- 3 Let  $\{X_t\}_{t \geq 0}$  be a continuous-time Markov process with finite state space  $\mathcal{X} = \{1, \dots, n\}$  and transition intensities matrix  $\Lambda = [\lambda_{i,j}]_{i,j \in \mathcal{X}}$ . We can embed this process into  $\mathbb{R}^n$  by representing each state  $i \in \mathcal{X}$  by the  $i$ th canonical basis vector  $e_i = (0, 0, \dots, 0, 1, 0, \dots, 0)^\top \in \mathbb{R}^n$ , where only the  $i$ th coordinate is set to 1 and the rest are zero. Let  $\{\tilde{X}_t\}_{t \geq 0}$  denote the resulting  $\mathbb{R}^n$ -valued Markov process with state space  $\tilde{\mathcal{X}} := \{e_1, \dots, e_n\} \subset \mathbb{R}^n$ .

- (a) Prove that, for any  $0 \leq s < t$  and any  $\tilde{x} \in \tilde{\mathcal{X}}$ ,

$$\mathbf{E}[\tilde{X}_t | \tilde{X}_s = \tilde{x}] = [e^{\Lambda(t-s)}]^\top \tilde{x}.$$

- (b) For each  $t \geq 0$ , let  $\mathcal{F}_t$  denote the  $\sigma$ -algebra generated by  $\tilde{X}_{[0,t]} := \{\tilde{X}_s\}_{0 \leq s \leq t}$ . Consider the process  $\{M_t\}$  defined by

$$M_t := \tilde{X}_t - \tilde{X}_0 - \int_0^t \Lambda^\top \tilde{X}_s ds.$$

Prove that  $\{M_t\}$  is an  $\{\mathcal{F}_t\}$ -martingale, i.e., for any  $0 \leq s < t$ ,

$$\mathbf{E}[M_t - M_s | \mathcal{F}_s] = 0.$$

- 4 In this problem, we will consider the simplest construction of a stochastic integral, due to Wiener, to illustrate the key ideas.

Let  $W = (W_t)_{t \geq 0}$  be a standard one-dimensional Brownian motion. Our goal is to give meaning to an integral of the form

$$I(f) = \int_0^T f(t) dW_t$$

for any *deterministic* function  $f : [0, T] \rightarrow \mathbb{R}$  which is square-integrable, i.e.,

$$\|f\|_{L^2[0, T]} := \left( \int_0^T |f(t)|^2 dt \right)^{1/2} < \infty.$$

(The extension to square-integrable adapted random processes is due to K. Itô, and bears his name.) Let  $S[0, T]$  be the space of all *step functions* on the interval  $[0, T]$  – that is,  $f \in S[0, T]$  if and only if there exist finitely many time instants  $0 = t_0 < t_1 < \dots < t_{n-1} < t_n = T$ , such that  $f(t)$  is constant on each interval  $[t_i, t_{i+1})$ ,  $i = 0, \dots, n-1$ . For such an  $f$ , we *define*

$$I(f) := \sum_{i=0}^{n-1} f(t_i) (W_{t_{i+1}} - W_{t_i}).$$

Observe that, while  $f$  was deterministic,  $I(f)$  is a *random variable*. Now, one of the basic results in functional analysis is that the step functions in  $S[0, T]$  are *dense* in  $L^2[0, T]$  (the Hilbert space of all square-integrable real-valued functions on  $[0, T]$ ), i.e., for any  $f \in L^2[0, T]$  we can find a sequence  $\{f_n\}_{n=1}^\infty$  of step functions, such that  $\|f_n - f\|_{L^2[0, T]} \xrightarrow{n \rightarrow \infty} 0$ . Using this fact, we define the stochastic integral  $I(f) = \lim_{n \rightarrow \infty} I(f_n)$ . We will not worry about the details of this passage to the limit, but will instead investigate the properties of the integral  $I(f)$  on  $S[0, T]$ .

(a) Prove the following properties:

(i) For any two  $f_1, f_2 \in S[0, T]$  and any pair of coefficients  $c_1, c_2$ ,  $I(c_1 f_1 + c_2 f_2) = c_1 I(f_1) + c_2 I(f_2)$ ; moreover, the random variables  $I(f)$ ,  $f \in S[0, T]$ , are jointly Gaussian.

(ii) For any two disjoint subintervals  $A, B$  of  $[0, T]$ , the random variables  $I(\mathbf{1}_A)$  and  $I(\mathbf{1}_B)$  are independent.

(iii) For any  $f_1, f_2 \in S[0, T]$ ,

$$\mathbf{E}[I(f_1)I(f_2)] = \langle f_1, f_2 \rangle_{L^2[0, T]} := \int_0^T f_1(t)f_2(t)dt,$$

and in particular  $\mathbf{E}[I^2(f)] = \|f\|_{L^2[0, T]}^2$ .

(iv) For any  $f \in S[0, T]$ ,  $I(f) \sim N(0, \|f\|_{L^2[0, T]}^2)$ .

(b) As noted earlier, all of these results continue to hold true for every  $f \in L^2[0, T]$ . With that in mind, prove the following: Let  $\{\varphi_i\}_{i=1}^\infty$  be a complete orthonormal system of functions in  $L^2[0, T]$ , i.e.,  $\langle \varphi_i, \varphi_j \rangle_{L^2[0, T]} = \delta_{ij}$  for all  $i, j$ , where  $\delta_{ij}$  is the Kronecker symbol. Then the random variables  $I(\varphi_1), I(\varphi_2), \dots$  are i.i.d.  $N(0, 1)$ .